

Mathematical modelling, Exam 2

5. 7. 2019

1. The system of equations $2x - y + z = 3$ and $-x + 2y - z = 1$ can be expressed in the form $Ax = b$.
 - (a) Find the Moore-Penrose inverse of A , A^\dagger .
 - (b) Describe the property uniquely characterizing the point $A^\dagger b$ with respect to the system.
 - (c) Construct any single matrix, which has the following matrices as their generalized inverses: $\begin{bmatrix} 3 & 2 & 0 & 0 \\ 1 & -1 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 3 & 2 \\ 0 & 0 & 1 & -1 \end{bmatrix}$.

Solution.

- (a) The matricial form of the system is the following:

$$\underbrace{\begin{bmatrix} 2 & -1 & 1 \\ -1 & 2 & -1 \end{bmatrix}}_A \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \underbrace{\begin{bmatrix} 3 \\ 1 \end{bmatrix}}_b.$$

Since $\text{rank } A = 2$, also $\text{rank}(AA^T) = 2$ and hence A^\dagger is equal to

$$\begin{aligned} A^\dagger &= A^T(AA^T)^{-1} = \begin{bmatrix} 2 & -1 \\ -1 & 2 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 6 & -5 \\ -5 & 6 \end{bmatrix}^{-1} \\ &= \begin{bmatrix} 2 & -1 \\ -1 & 2 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} \frac{6}{11} & \frac{5}{11} \\ \frac{5}{11} & \frac{6}{11} \end{bmatrix} \\ &= \begin{bmatrix} \frac{7}{11} & \frac{4}{11} \\ \frac{4}{11} & \frac{7}{11} \\ \frac{1}{11} & -\frac{1}{11} \end{bmatrix}. \end{aligned}$$

- (b) Since $A \in \mathbb{R}^{2 \times 3}$ and $\text{rank } A = 2$, it follows that the system $Ax = b$ is solvable and the kernel of A is one-dimensional. Hence, there is a one-dimensional family of solutions of the system $Ax = b$. The vector $A^\dagger b$ is the solution of the system of the smallest norm among all solutions.

- (c) The matrix A is of size 4×2 . By construction of some generalized inverses, the matrix

$$\begin{bmatrix} 3 & 2 & 0 & 0 \\ 1 & -1 & 0 & 0 \end{bmatrix}$$

is a generalized inverse of any matrix of the form

$$\begin{bmatrix} \begin{bmatrix} 3 & 2 \\ 1 & -1 \end{bmatrix}^{-1} \\ X \end{bmatrix},$$

where $X \in \mathbb{R}^{2 \times 2}$ is any matrix, and the matrix

$$\begin{bmatrix} 0 & 0 & 3 & 2 \\ 0 & 0 & 1 & -1 \end{bmatrix}$$

is a generalized inverse of any matrix of the form

$$\begin{bmatrix} Y \\ \begin{bmatrix} 3 & 2 \\ 1 & -1 \end{bmatrix}^{-1} \end{bmatrix},$$

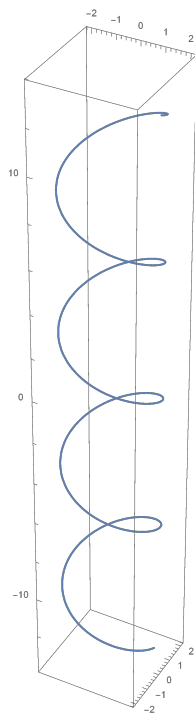
where $Y \in \mathbb{R}^{2 \times 2}$ is any matrix. Hence,

$$A = \begin{bmatrix} \begin{bmatrix} 3 & 2 \\ 1 & -1 \end{bmatrix}^{-1} \\ \begin{bmatrix} 3 & 2 \\ 1 & -1 \end{bmatrix}^{-1} \end{bmatrix} = \begin{bmatrix} -\frac{1}{5} & \frac{2}{5} \\ \frac{1}{5} & -\frac{2}{5} \\ \frac{1}{5} & -\frac{2}{5} \\ \frac{1}{5} & -\frac{2}{5} \end{bmatrix}.$$

2. Given the parametric curve $\gamma(t) = [2 \cos(t), 2 \sin(t), -t]^T$:
- Sketch/describe γ .
 - Parameterize γ with a natural parameter.
 - Find the length of γ between points $(2, 0, 0)$ and $(2, 0, 2\pi)$.

Solution.

- The sketch of γ is the following:



- (b) The natural parameter $s(t)$, which measures the arc length between the points $\gamma(0)$ and $\gamma(t)$ is

$$\begin{aligned}
 s(t) &= \int_0^t \|\gamma'(u)\| \, du = \int_0^t \|(-2 \sin u, 2 \cos u, -1)\| \, du \\
 &= \int_0^t \sqrt{4 \sin^2 u + 4 \cos^2 u + 1} \, du \\
 &= \int_0^t \sqrt{5} \, du = t\sqrt{5}.
 \end{aligned}$$

Hence, $t(s) = \frac{s}{\sqrt{5}}$ and the parametrization of the curve with the natural parameter s is

$$\gamma(s) = \left(2 \cos \left(\frac{s}{\sqrt{5}} \right), 2 \sin \left(\frac{s}{\sqrt{5}} \right), -\frac{s}{\sqrt{5}} \right).$$

- (c) The point $(2, 0, 0)$ corresponds to $t = 0$, while $(2, 0, 2\pi)$ to $t = -2\pi$. Hence, the arc length between this points equals by symmetry to $s(2\pi) = 2\pi\sqrt{5}$.

3. Find the solution y of the differential equation $x^2y' + xy + 3 = 0$ with the initial condition $y(1) = 1$.

Solution. First we solve the homogeneous part of the DE:

$$\begin{aligned}x^2y' + xy = 0 &\Rightarrow -\frac{dy}{y} = \frac{dx}{x} \Rightarrow -\ln|y| = \ln|x| + k \\ &\Rightarrow y_h(x) = \frac{K}{x},\end{aligned}$$

where $k, K \in \mathbb{R}$ are constants. Now we have to determine one particular solution. By variation of constants the form of the particular solution is

$$y_p(x) = \frac{K(x)}{x},$$

where $K(x)$ is a function of x . Thus,

$$y_p'(x) = \frac{K'(x)x - K(x)}{x^2} \tag{1}$$

and plugging (1) into the initial DE we get

$$x^2 \cdot \frac{K'(x)x - K(x)}{x^2} + x \frac{K(x)}{x} + 3 = 0.$$

Equivalently,

$$K'(x)x + 3 = 0. \tag{2}$$

We solve the DE (2) by separation of variables:

$$-\frac{dK}{3} = \frac{dx}{x} \Rightarrow -\frac{1}{3}K = \ln|x| \Rightarrow K = \ln \frac{1}{|x|^3}.$$

Since in the initial condition $x > 0$, we have $K = \ln \frac{1}{x^3}$ and $y_p(x) = \ln \frac{1}{x^3} \cdot \frac{1}{x}$. So, the general solution of the DE is

$$y(x) = y_h(x) + y_p(x) = \left(K + \ln \frac{1}{x^3} \right) \frac{1}{x}.$$

The solution which passes through the point $(1, 1)$ is

$$y(1) = 1 = K + \ln 1 \Rightarrow K = 1 \Rightarrow y(x) = \left(1 + \ln \frac{1}{x^3} \right) \frac{1}{x}.$$

4. Solve the following system of differential equations:

$$\begin{aligned}x'(t) &= -2x(t) + 5y(t), \\y'(t) &= x(t) + 2y(t),\end{aligned}$$

with the initial conditions $x(0) = y(0) = 1$.

Solution. The matricial form of the system is the following:

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \underbrace{\begin{bmatrix} -2 & 5 \\ 1 & 2 \end{bmatrix}}_A \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}.$$

We compute the eigenvalues of A :

$$\begin{aligned}\det(A - \lambda I_2) &= \det \begin{bmatrix} -2 - \lambda & 5 \\ 1 & 2 - \lambda \end{bmatrix} = (-2 - \lambda)(2 - \lambda) - 5 \\ &= \lambda^2 - 9 = (\lambda - 3)(\lambda + 3).\end{aligned}$$

Thus the eigenvalues are $\lambda_1 = 3$ and $\lambda_2 = -3$. The kernel of

$$A - \begin{bmatrix} 3 & 0 \\ 0 & 3 \end{bmatrix} = \begin{bmatrix} -5 & 5 \\ 1 & -1 \end{bmatrix}$$

contains the vector

$$u_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$

The kernel of

$$A - \begin{bmatrix} -3 & 0 \\ 0 & -3 \end{bmatrix} = \begin{bmatrix} 1 & 5 \\ 1 & 5 \end{bmatrix}$$

contains the vector

$$u_2 = \begin{bmatrix} -5 \\ 1 \end{bmatrix}.$$

So, the general solution of the system is

$$\begin{bmatrix} x \\ y \end{bmatrix} = C_1 \cdot e^{3t} \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} + C_2 \cdot e^{-3t} \cdot \begin{bmatrix} -5 \\ 1 \end{bmatrix},$$

where C_1 and C_2 are constants. The solution, which satisfies $x(0) = y(0) = 1$, is:

$$\begin{aligned} C_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + C_2 \begin{bmatrix} -5 \\ 1 \end{bmatrix} &= \begin{bmatrix} 1 \\ 1 \end{bmatrix} &\Rightarrow C_1 - 5C_2 = 1, \quad C_1 + C_2 = 1 \\ & &\Rightarrow C_1 = 1, \quad C_2 = 0. \end{aligned}$$